
Worked example

Impulse Response

ELEC3004 / ELEC7312

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Adapted from Slides Prof. Andrew Bradley



Create change

Blackbox System

A **signal** can be observed output from an unknown linear time-invariant **system**



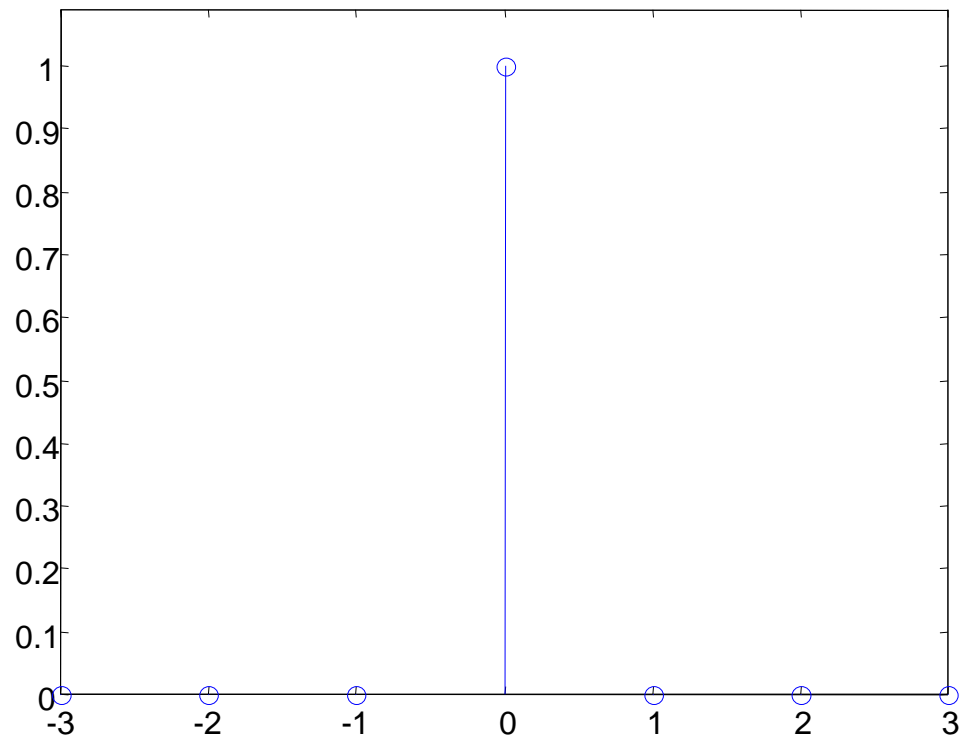
How can we characterise it?

Impulse Functions

Discrete-time

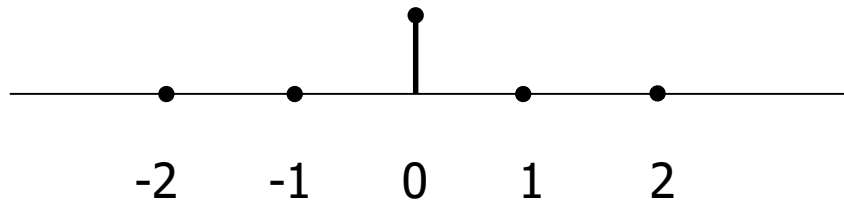
- unit sample, or unit impulse
- $\delta[n]$
- unit area

$$\delta[n] = \begin{cases} 0, & n \neq 0; \\ 1, & n = 0. \end{cases}$$



Example: Discrete Sequence

$$\{x[n]\}_{-2}^2 = [0 \quad 0 \quad 1 \quad 0 \quad 0]$$

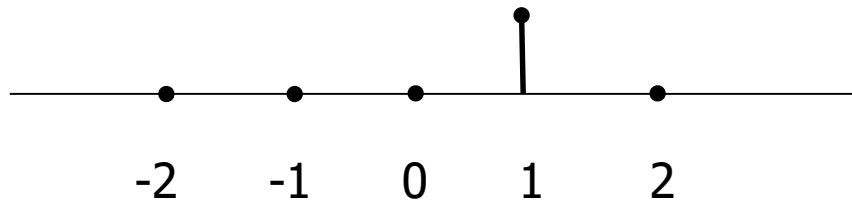


$$x[n] = x[-2]\delta[n+2] + x[-1]\delta[n+1] + x[0]\delta[n] + x[1]\delta[n-1] + x[2]\delta[n-2]$$

$$x[n] = \delta[n] \quad \leftarrow \text{Impulse signal}$$

Example: Discrete Sequence

$$\{x[n]\}_{-2}^2 = [0 \quad 0 \quad 0 \quad 1 \quad 0]$$

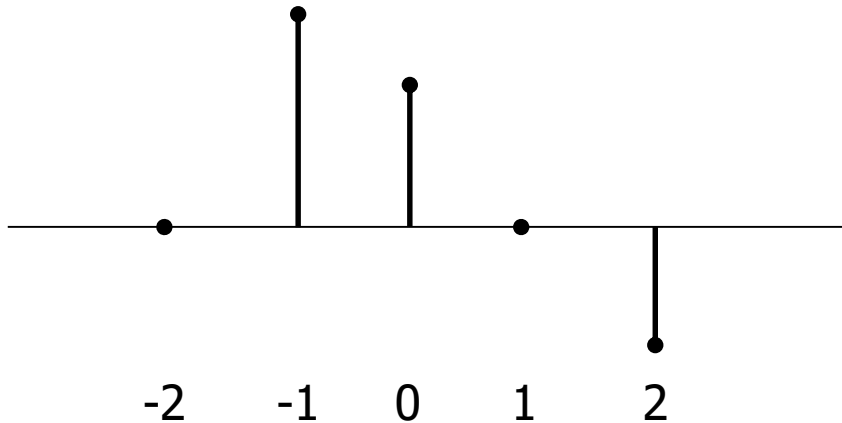


$$x[n] = x[-2]\delta[n+2] + x[-1]\delta[n+1] + x[0]\delta[n] + x[1]\delta[n-1] + x[2]\delta[n-2]$$

$$x[n] = \delta[n-1] \quad \leftarrow \text{Signal will arrive at } n=1, \text{ so it is a delay}$$

Example: Discrete Sequence

$$\{x[n]\}_{-2}^2 = [0 \quad 3 \quad 2 \quad 0 \quad -1]$$

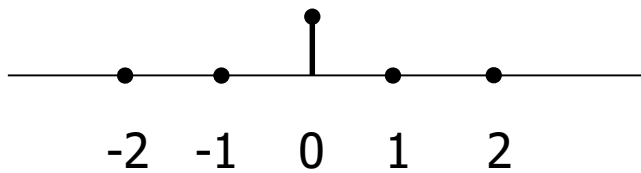


$$x[n] = x[-2]\delta[n+2] + x[-1]\delta[n+1] + x[0]\delta[n] + x[1]\delta[n-1] + x[2]\delta[n-2]$$

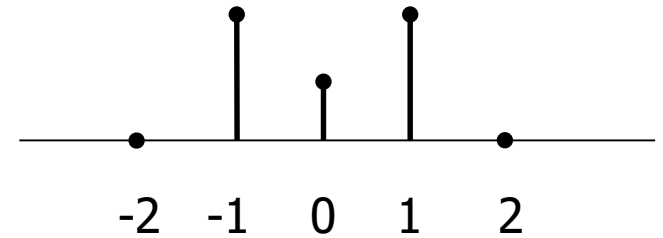
$$x[n] = 3\delta[n+1] + 2\delta[n] - \delta[n-2]$$

Example: Impulse Response

$$\{x[n]\}_{-2}^2 = [0 \quad 0 \quad 1 \quad 0 \quad 0]$$

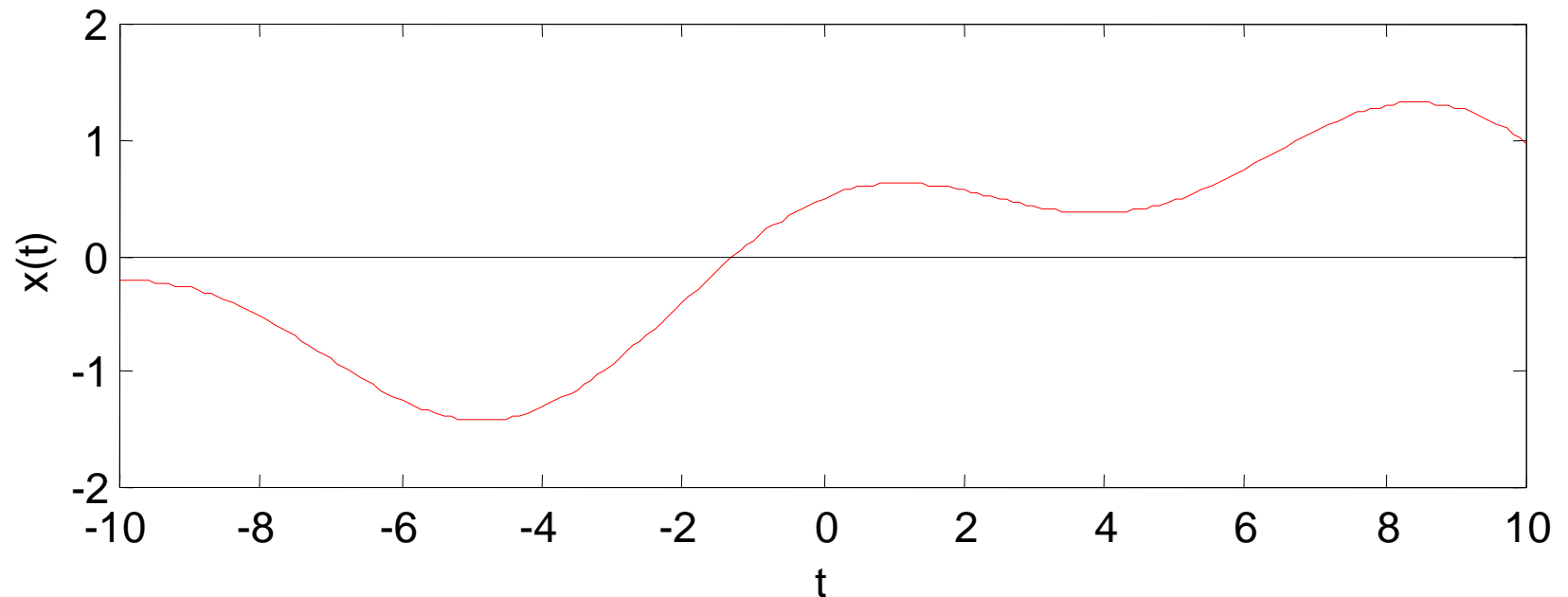


$$x[n] = \delta[n]$$

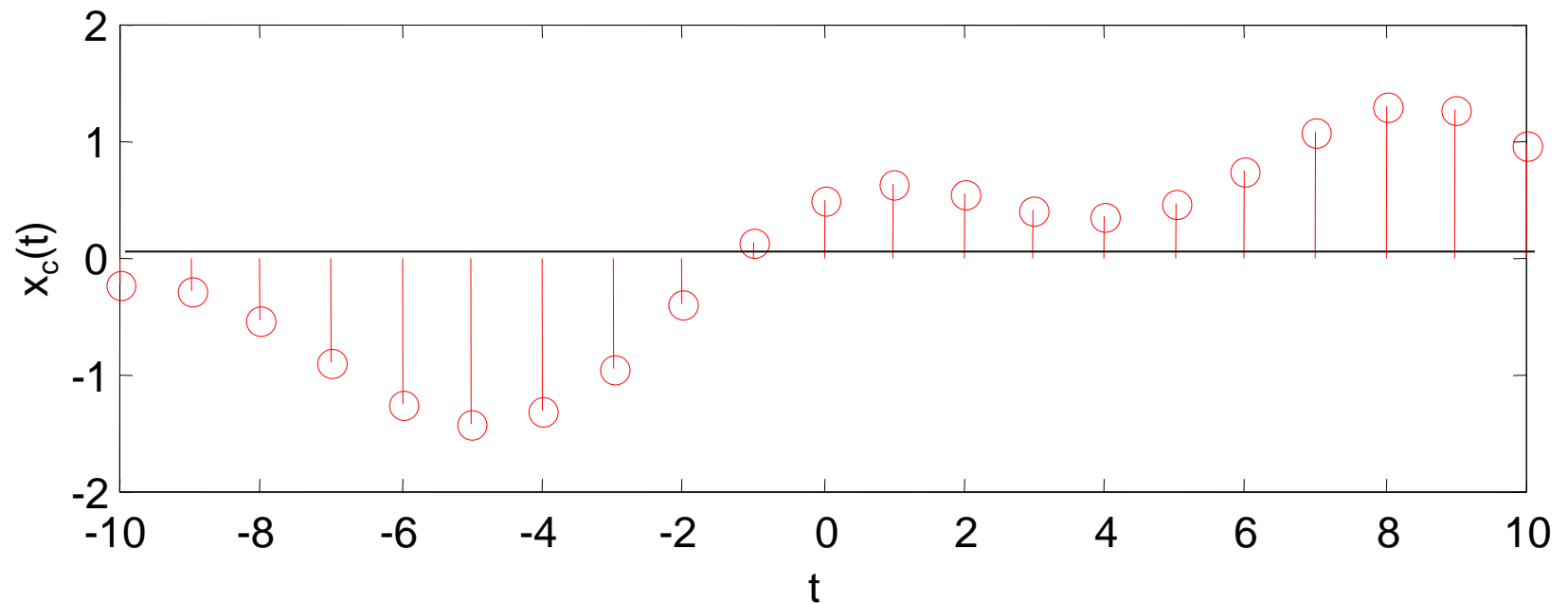


$$\begin{aligned} y[n] &= h[n] \\ &= 2*\delta[n+1] + \delta[n] + 2*\delta[n-1] \end{aligned}$$

Continuous-time



Discrete-time



Any signal is just a superposition of weighted impulses

Principle of Superposition

Combination of

- Scaling and
- **Additivity**

e.g., 2 inputs & 2 constants (a & b)

$$H\{ax_1[n] + bx_2[n]\} = aH\{x_1[n]\} + bH\{x_2[n]\}$$

Linear systems obey the principle of superposition
i.e., they obey associative and distributive rules

Time Invariance

Conceptually,

- System does not change over time
- e.g., Circuit R & C fixed

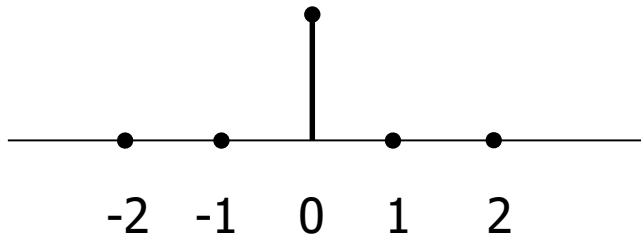
Formally,

- **Time shift in the input causes an**
- **Identical time shift in the output (only)**
- $y[n - n_0] = H\{x[n - n_0]\}$

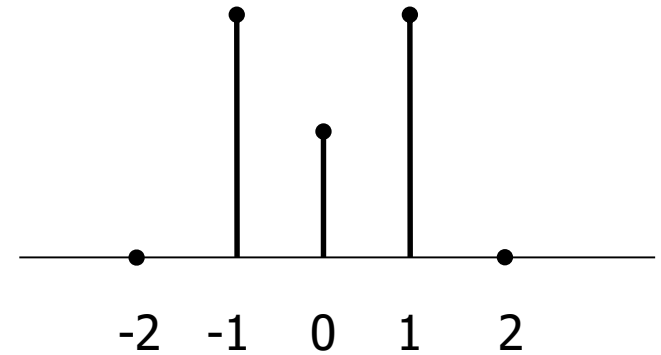
Example: Impulse Response

$$\{x[n]\}_{-2}^2 = [0 \quad 0 \quad 2 \quad 0 \quad 0]$$

Scaling



$$x[n] = 2\delta[n]$$

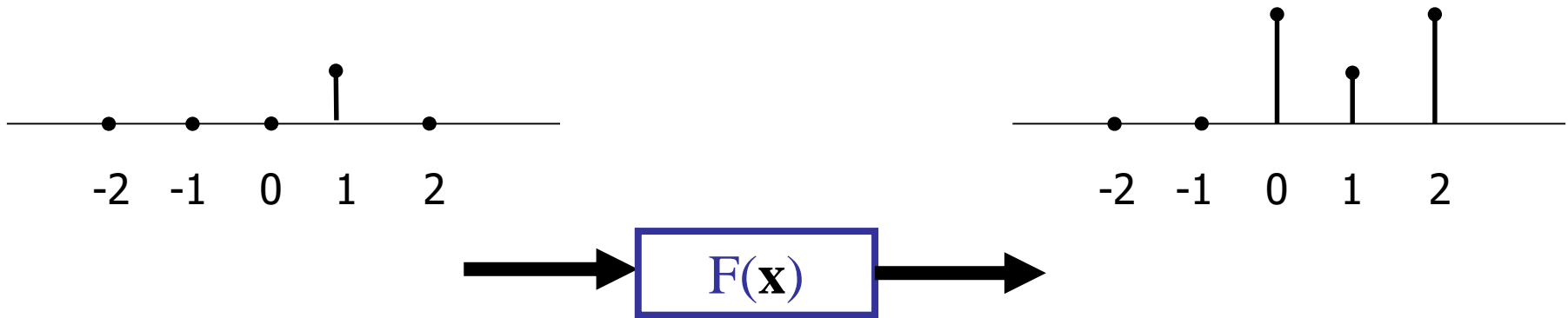


$$\begin{aligned} y[n] &= h[n] \\ &= 4\delta[n+1] + 2\delta[n] + 4\delta[n-1] \end{aligned}$$

Example: Impulse Response

$$\{x[n]\}_{-2}^2 = [0 \quad 0 \quad 2 \quad 0 \quad 0]$$

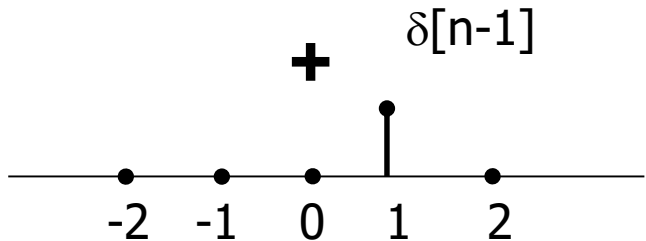
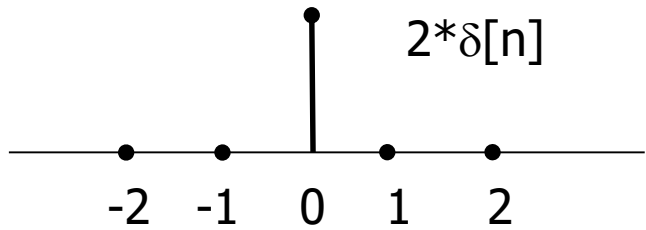
Time Shift



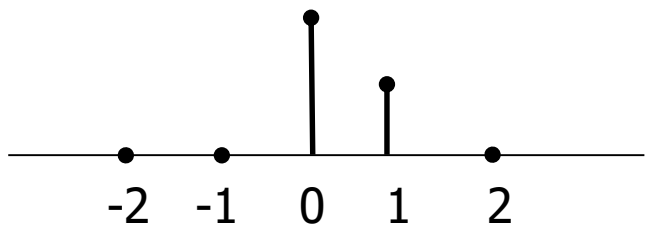
$$x[n] = \delta[n-1]$$

$$\begin{aligned} y[n] &= h[n] \\ &= 2*\delta[n] + \delta[n-1] + 2*\delta[n-2] \end{aligned}$$

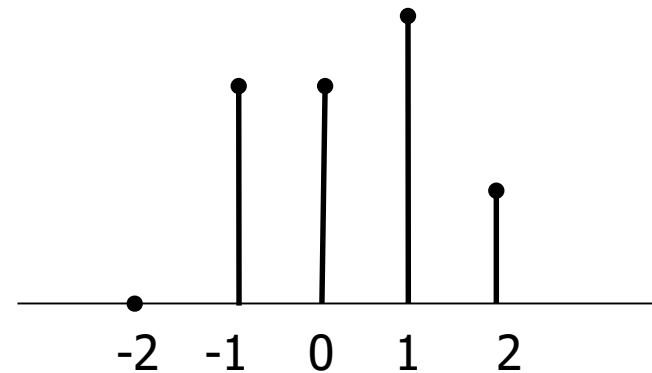
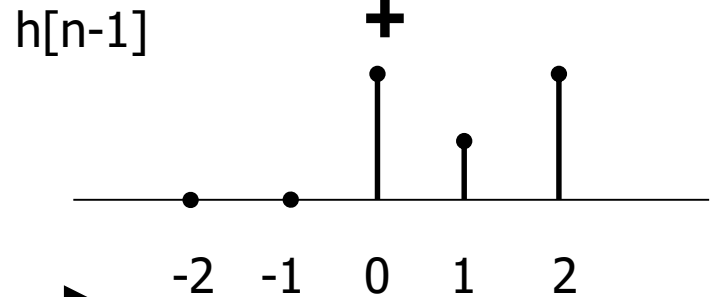
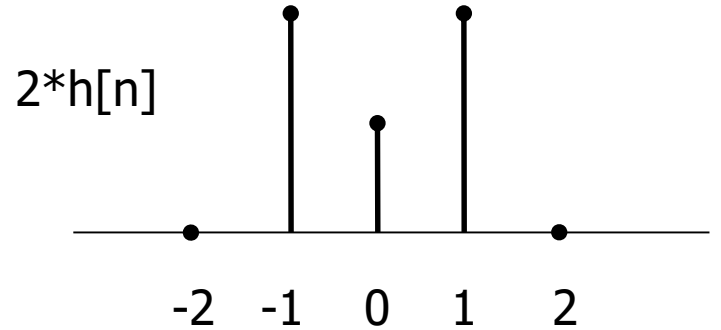
Example: Impulse Response



$x[n] = 2*\delta[n] + \delta[n-1]$



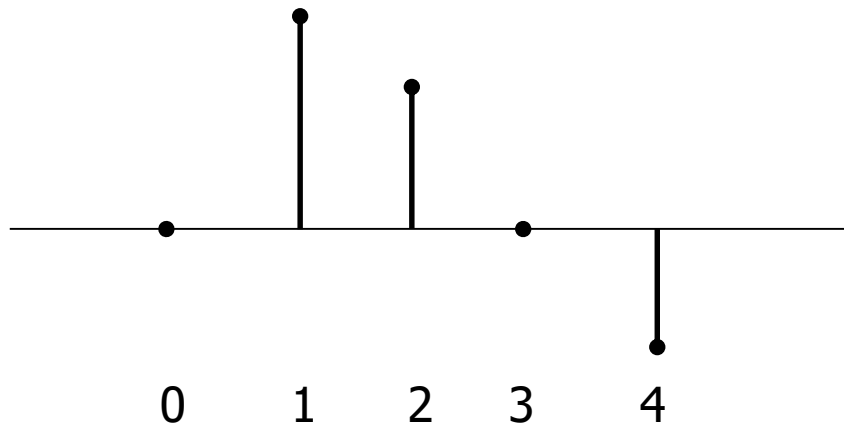
$F(\mathbf{x})$



$y[n] = 2*h[n] + h[n-1]$

Example: Impulse Response

$$\{x[n]\}_0^4 = [0 \quad 3 \quad 2 \quad 0 \quad -1]$$



$$\begin{aligned} x[n] &= x[0]\delta[n-0] + x[1]\delta[n-1] + x[2]\delta[n-2] + x[3]\delta[n-3] + x[4]\delta[n-4] \\ &= 0*\delta[n-0] + 3*\delta[n-1] + 2*\delta[n-2] + 0*\delta[n-3] + -1*\delta[n-4] \end{aligned}$$

$$\begin{aligned} y[n] &= 0*h[n-0] + 3*h[n-1] + 2*h[n-2] + 0*h[n-3] + -1*h[n-4] \\ &= x[0]h[n-0] + x[1]h[n-1] + x[2]h[n-2] + x[3]h[n-3] + x[4]h[n-4] \end{aligned}$$

$$y[n] = \sum_{m=0}^{\infty} h[n-m]x[m] = h[n] * x[n]$$