

→ SRW - 3/13/2013 - LINEAR DYNAMICAL SYSTEMS

LECTURE

(Kilove!)

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(cat style)

→ Impulse response example

$$\underbrace{(D^2 + 3D + 2)}_{\text{2nd order}} y(t) = \underline{D} \cdot x(t)$$

$D^2 + 3D + 2$  - characteristic polynomial →

$$\lambda = -1, -2$$

$$D^2 + 3D + 2 \rightarrow (\lambda + 1)(\lambda + 2)$$

$$\mathcal{L}^{-1} \Rightarrow y(t) = c_1 e^{-t} + c_2 e^{-2t}$$

$$Dy(0) = 1$$

$$y(0) = 0$$

$$\Rightarrow c_1 = 1, c_2 = -1$$

$$\hookrightarrow y(t) = e^{-t} - e^{-2t} = \underline{\underline{h(t)}}$$

## → 2nd order Systems

$$a y'' + b y' + c y = 0$$

$$\mathcal{L}: a \left[ s^2 Y(s) - s y(0) - y'(0) \right]$$

$$+ b \left[ s Y(s) - y(0) \right]$$

$$+ c \left[ Y(s) \right] = 0$$

⇒ Solve for  $Y(s)$

$$Y(s) = \frac{a y(0) \cdot s + a y'(0) + b y(0)}{a s^2 + b s + c}$$

$$= \frac{\alpha s + \beta}{a s^2 + b s + c}$$

$$= \frac{(\alpha/a) s + (\beta/a)}{s^2 + (b/a) s + (c/a)}$$

$$Y(s) = \frac{\bar{A}s + \bar{B}}{s^2 + \frac{B}{A}s + \frac{C}{A}}$$

$$\omega_n^2 = \frac{C}{A}$$

$$2\zeta\omega_n = \frac{B}{A} \Rightarrow \zeta = \frac{B}{2\sqrt{AC}}$$

$$Y(s) = \frac{\bar{A}s + \bar{B}}{s^2 + 2\zeta\omega_n s + \omega_n^2}$$

$$\bar{A} = 0, \bar{B} = \omega_n^2$$

**1 UNDERDAMPED**  $0 < \zeta < 1$

$$\frac{Y(s)}{\text{underdamped}} = \frac{\omega_n^2}{(s + \zeta\omega_n + j(\omega_n\sqrt{1-\zeta^2})) (s + \zeta\omega_n - j(\omega_n\sqrt{1-\zeta^2}))}$$

I ↑  $\omega_n$  ↓ II  
NOTE THE SIGN - ITS A SIGNAL!

UNIT IMPULSE =  $\frac{1}{s}$

STEP INPUT =  $\frac{1}{s^2}$

$$\mathcal{L}^{-1}[I] = e^{-\zeta\omega_n t} \cdot \cos(\omega_d t)$$

$$\mathcal{L}^{-1}[II] = e^{-\zeta\omega_n t} \cdot \sin(\omega_d t)$$

II CRITICALLY DAMPED  $\zeta = 1$

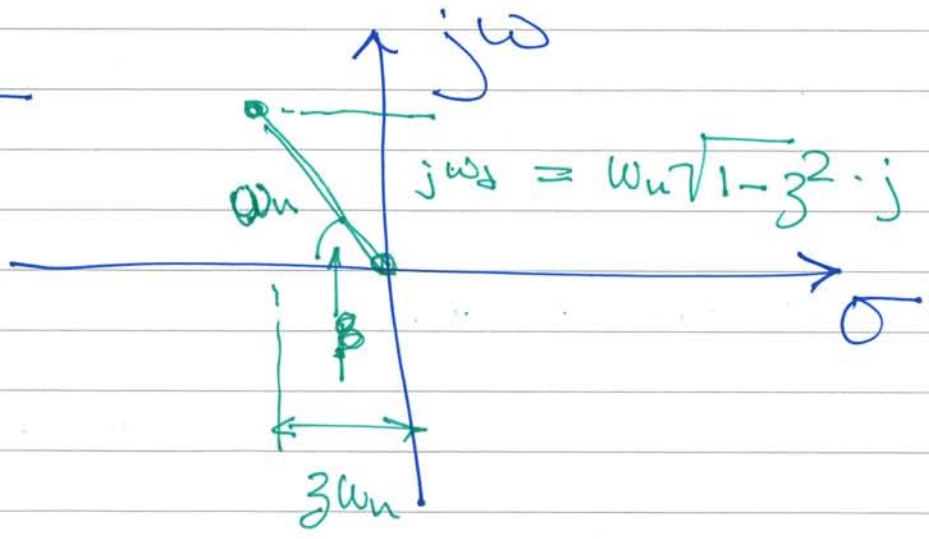
$\rightarrow C(s) = \frac{1}{s} \rightarrow P(s) = \frac{\omega_n^2}{(s + \omega_n)^2 \cdot s}$

$e(t) = 1 - e^{-\omega_n t} (1 + \omega_n t)$

III OVERDAMPED CASE ( $\zeta > 1$ )

$e(t) = 1 - \exp[-(\zeta - \sqrt{\zeta^2 - 1}) \omega_n t]$

S-PLANE



$s = \sigma + jw$