



Analog Filters

ELEC 3004: **Systems**: Signals & Controls
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Lecture 13

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Goals for the Week

- Continue of Discussion of the z-Transform
- Noise
- Introduce Analog Filters (Today) → Friday
 - Frequency Response of an LTIC and LTID System
 - Butterworth
 - Chebyshev
- Digital Filters IIR Filters
 - Design of IIR Filters from Analog Filters
 - FIR Filter

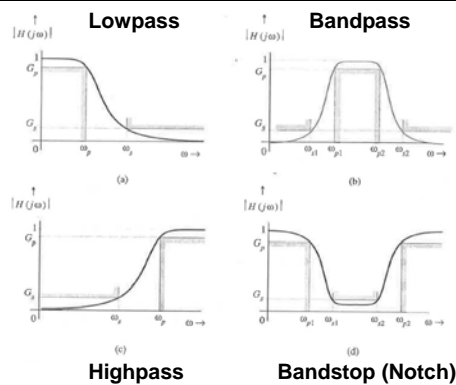


Today...

Week	Date	Lecture Title
1	27-Feb	Introduction
	1-Mar	Systems Overview
2	6-Mar	Signals & Signal Models
	8-Mar	System Models
3	13-Mar	Linear Dynamical Systems
	15-Mar	Sampling & Data Acquisition
4	20-Mar	Time Domain Analysis of Continuous Time Systems
	22-Mar	System Behaviour & Stability
5	27-Mar	Signal Representation
	29-Mar	Holiday
6	10-Apr	Frequency Response
	12-Apr	- Transform
7	17-Apr	Noise & Filtering
	19-Apr	Analog Filters
8	24-Apr	Discrete-Time Signals
	26-Apr	Discrete-Time Systems
9	1-May	Digital Filters & IIR/FIR Systems
	3-May	Fourier Transform & DTFT
10	8-May	State-Space
	10-May	Controllability & Observability
11	15-May	Introduction to Digital Control
	17-May	Stability of Digital Systems
12	22-May	PID & Computer Control
	24-May	Information Theory & Communications
13	29-May	Applications in Industry
	31-May	Summary and Course Review



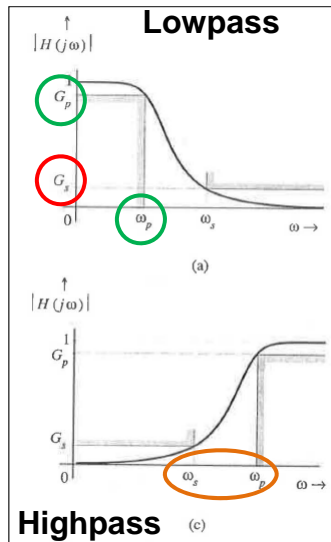
Filters



- *Frequency-shaping filters*: LTI systems that change the shape of the spectrum
- *Frequency-selective filters*: Systems that pass some frequencies undistorted and attenuate others



Filters



Specified Values:

- G_p = minimum passband gain

Typically:

$$G_p = \frac{1}{\sqrt{2}} = -3dB$$

- G_s = maximum stopband gain

- **Low**, not zero (sorry!)
- For realizable filters, the gain cannot be zero over a finite band (Paley-Wiener condition)

- **Transition Band:**

transition from the passband to the stopband $\rightarrow \omega_p \neq \omega_s$



Filter Design & z-Transform

Filter Type	Mapping	Design Parameters
Low-pass	$z^{-1} \rightarrow \frac{z^{-1} - \alpha}{1 - \alpha z^{-1}}$	$\alpha = \frac{\sin[(\omega_c - \omega'_c)/2]}{\sin[(\omega_c + \omega'_c)/2]}$ ω'_c = desired cutoff frequency
High-pass	$z^{-1} \rightarrow -\frac{z^{-1} + \alpha}{1 + \alpha z^{-1}}$	$\alpha = -\frac{\cos[(\omega_c + \omega'_c)/2]}{\cos[(\omega_c - \omega'_c)/2]}$ ω'_c = desired cutoff frequency
Bandpass	$z^{-1} \rightarrow \frac{z^{-2} - [2\alpha\beta/(\beta + 1)]z^{-1} + [(\beta - 1)/(\beta + 1)]}{[(\beta - 1)/(\beta + 1)]z^{-2} - [2\alpha\beta/(\beta + 1)]z^{-1} + 1}$	$\alpha = \frac{\cos[(\omega_{c2} + \omega_{c1})/2]}{\cos[(\omega_{c2} - \omega_{c1})/2]}$ $\beta = \cot[(\omega_{c2} - \omega_{c1})/2] \tan(\omega_c/2)$ ω_{c1} = desired lower cutoff frequency ω_{c2} = desired upper cutoff frequency
Bandstop	$z^{-1} \rightarrow \frac{z^{-2} - [2\alpha/(\beta + 1)]z^{-1} + [(1 - \beta)/(1 + \beta)]}{[(1 - \beta)/(1 + \beta)]z^{-2} - [2\alpha/(\beta + 1)]z^{-1} + 1}$	$\alpha = \frac{\cos[(\omega_{c1} + \omega_{c2})/2]}{\cos[(\omega_{c1} - \omega_{c2})/2]}$ $\beta = \tan[(\omega_{c2} - \omega_{c1})/2] \tan(\omega_c/2)$ ω_{c1} = desired lower cutoff frequency ω_{c2} = desired upper cutoff frequency



Butterworth Filters

- Butterworth: Smooth in the pass-band
- The amplitude response $|H(j\omega)|$ of an n^{th} order Butterworth low pass filter is given by:

$$|H(j\omega)| = \frac{1}{\sqrt{1 + \left(\frac{\omega}{\omega_c}\right)^{2n}}}$$

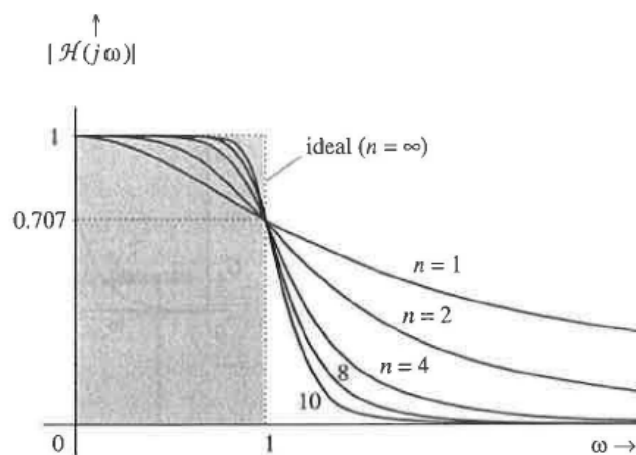
- The normalized case ($\omega_c=1$)

$$|\mathcal{H}(j\omega)| = \frac{1}{\sqrt{1 + \omega^{2n}}} \quad \Rightarrow \quad \mathcal{H}(j\omega)\mathcal{H}(-j\omega) = |\mathcal{H}(j\omega)|^2 = \frac{1}{1 + \omega^{2n}}$$

Recall that: $|H(j\omega)|^2 = H(j\omega)H(-j\omega)$

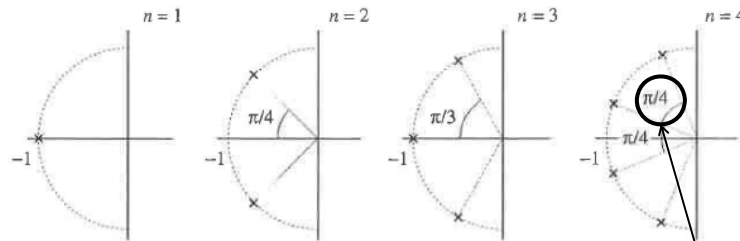


Butterworth Filters



Butterworth Filters of Increasing Order: Seeing this Using a Pole-Zero Diagram

- Increasing the order, increases the number of poles:



→ Odd orders ($n=1,3,5\dots$):

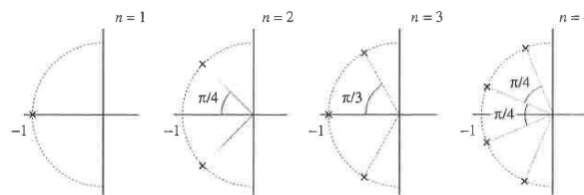
- Have a pole on the Real Axis

→ Even orders ($n=2,4,6\dots$):

- Have a pole on the off axis

Angle between poles:
 $\frac{\pi}{n}$

Butterworth Filters: Pole-Zero Diagram



- Since $H(s)$ is stable and causal, its poles must lie in the LHP
- Poles of $-H(s)$ are those in the RHP
- Poles lie on the unit circle (for a normalized filter)

→
$$H(s) = \frac{1}{(s - s_1)(s - s_2)\dots(s - s_n)}$$

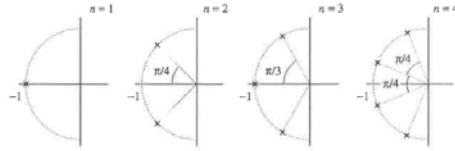
Where:

$$s_k = e^{j\frac{\pi}{2n}(2k+n-1)}$$

$$= \cos \frac{\pi}{2n}(2k+n-1) + j \sin \frac{\pi}{2n}(2k+n-1) \quad k = 1, 2, 3, \dots, n$$

n is the order of the filter

Butterworth Filters: 4th Order Filter Example



- Plugging in for $n=4$, $k=1, \dots, 4$:

$$\begin{aligned} \mathcal{H}(s) &= \frac{1}{(s + 0.3827 - j0.9239)(s + 0.3827 + j0.9239)(s + 0.9239 - j0.3827)(s + 0.9239 + j0.3827)} \\ &= \frac{1}{(s^2 + 0.7654s + 1)(s^2 + 1.8478s + 1)} \\ &= \frac{1}{s^4 + 2.6131s^3 + 3.4142s^2 + 2.6131s + 1} \end{aligned}$$

- We can generalize → Butterworth Table

n	a_1	a_2	a_3	a_4	a_5
2	1.41421356				
3	2.00000000	2.00000000			
4	2.61312593	3.41421356	2.61312593		
5	3.23606798	5.23606798	5.23606798	3.23606798	
6	3.86370331	7.46410162	9.14162017	7.46410162	3.86370331

This is for 3dB
bandwidth at
 $\omega_c=1$



Butterworth Filters: Scaling Back (from Normalized)

- Start with Normalized equation & Table
- Replace ω with $\frac{\omega}{\omega_c}$ in the filter equation
- For example:
for $f_c=100\text{Hz}$ → $\omega_c=200\pi$ rad/sec

From the Butterworth table: for $n=2$, $a_1=\sqrt{2}$
Thus:

$$\begin{aligned} H(s) &= \frac{1}{\left(\frac{s}{200\pi}\right)^2 + \sqrt{2}\left(\frac{s}{200\pi}\right) + 1} \\ &= \frac{1}{s^2 + 200\pi\sqrt{2}s + 40,000\pi^2} \end{aligned}$$



Butterworth: Determination of Filter Order

- Define G_x as the gain of a lowpass Butterworth filter at $\omega = \omega_x$
- Then:

$$\hat{G}_x = 20 \log_{10} |H(j\omega_x)| = -10 \log \left[1 + \left(\frac{\omega_x}{\omega_c} \right)^{2n} \right]$$

And thus:

$$\hat{G}_p = -10 \log \left[1 + \left(\frac{\omega_p}{\omega_c} \right)^{2n} \right]$$

$$\hat{G}_s = -10 \log \left[1 + \left(\frac{\omega_s}{\omega_c} \right)^{2n} \right]$$

Or alternatively:

$$\omega_c = \frac{\omega_p}{\left[10^{-\hat{G}_p/10} - 1 \right]^{1/2n}} \quad \& \quad \omega_c = \frac{\omega_s}{\left[10^{-\hat{G}_s/10} - 1 \right]^{1/2n}}$$

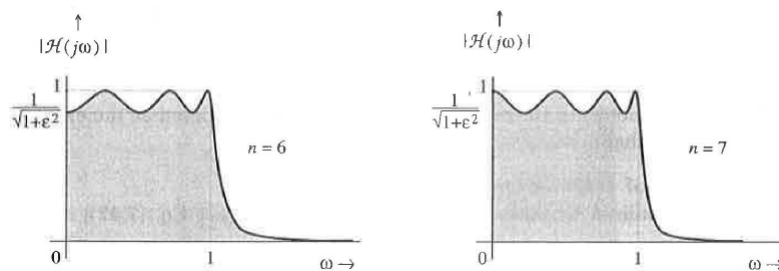
Solving for n gives:

$$n = \frac{\log \left[\left(10^{-\hat{G}_s/10} - 1 \right) / \left(10^{-\hat{G}_p/10} - 1 \right) \right]}{2 \log(\omega_s/\omega_p)}$$

PS. See Lathi 4.10 (p. 453) for an example in MATLAB



Chebyshev Filters



- **equal-ripple:**
Because all the ripples in the passband are of equal height
- If we reduce the ripple, the passband behaviour improves, but it does so at the cost of stopband behaviour



Chebyshev Filters

- Chebyshev Filters: Provide tighter transition bands (sharper cutoff) than the same-order Butterworth filter, but this is achieved at the expense of inferior passband behavior (rippling)

→ For the lowpass (LP) case: at higher frequencies (in the stopband), the Chebyshev filter gain is smaller than the comparable Butterworth filter gain by about **$6(n - 1)$ dB**

- The amplitude response of a normalized Chebyshev lowpass filter is:

$$|\mathcal{H}(j\omega)| = \frac{1}{\sqrt{1 + \epsilon^2 C_n^2(\omega)}}$$

Where $C_n(\omega)$, the n th-order Chebyshev polynomial, is given by:

$$C_n(\omega) = \cos(n \cos^{-1} \omega)$$

$$C_n(\omega) = \cosh(n \cosh^{-1} \omega)$$

and where C_n is given by:

n	$C_n(\omega)$
0	1
1	ω
2	$2\omega^2 - 1$
3	$4\omega^3 - 3\omega$
4	$8\omega^4 - 8\omega^2 + 1$
5	$16\omega^5 - 20\omega^3 + 5\omega$
6	$32\omega^6 - 48\omega^4 + 18\omega^2 - 1$



Normalized Chebyshev Properties

- It's normalized: The passband is $0 < \omega < 1$
- **Amplitude response:** has **ripples** in the passband and is **smooth** (monotonic) in the stopband
- **Number of ripples:** there is a total of n maxima and minima over the passband $0 < \omega < 1$

$$C_n^2(0) = \begin{cases} 0, & n : \text{odd} \\ 1, & n : \text{even} \end{cases} \quad \Rightarrow \quad |H(0)| = \begin{cases} 1, & n : \text{odd} \\ \frac{1}{\sqrt{1+\epsilon^2}}, & n : \text{even} \end{cases}$$

$$\epsilon: \text{ ripple height} \rightarrow r = \sqrt{1 + \epsilon^2}$$

$$\text{The Amplitude at } \omega=1: \frac{1}{r} = \frac{1}{\sqrt{1 + \epsilon^2}}$$

- For Chebyshev filters, the ripple r dB takes the place of G_p



Determination of Filter Order

- The gain is given by: $\hat{G} = -10 \log [1 + \epsilon^2 C_n^2(\omega)]$

Thus, the gain at ω_s is: $\epsilon^2 C_n^2(\omega_s) = 10^{-\hat{G}_s/10} - 1$

- Solving:

$$n = \frac{1}{\cosh^{-1}(\omega_s)} \cosh^{-1} \left[\frac{10^{-\hat{G}_s/10} - 1}{10^{\hat{\tau}/10} - 1} \right]^{1/2}$$

- General Case:

$$n = \frac{1}{\cosh^{-1}(\omega_s/\omega_p)} \cosh^{-1} \left[\frac{10^{-\hat{G}_s/10} - 1}{10^{\hat{\tau}/10} - 1} \right]^{1/2}$$



Chebyshev Pole Zero Diagram

- Whereas **Butterworth** poles lie on a **semi-circle**,
The poles of an n^{th} -order normalized **Chebyshev** filter lie on a **semiellipse** of the major and minor semiaxes:

$$a = \sinh \left(\frac{1}{n} \sinh^{-1} \left(\frac{1}{\epsilon} \right) \right) \quad \& \quad b = \cosh \left(\frac{1}{n} \sinh^{-1} \left(\frac{1}{\epsilon} \right) \right)$$

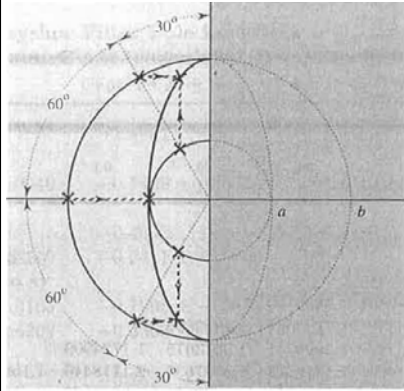
And the poles are at the locations:

$$H(s) = \frac{1}{(s - s_1)(s - s_2) \dots (s - s_n)}$$

$$s_k = -\sin \left[\frac{(2k-1)\pi}{2n} \right] \sinh x + j \cos \left[\frac{(2k-1)\pi}{2n} \right] \cosh x, \quad k = 1, \dots, n$$



Ex: Chebyshev Pole Zero Diagram for $n=3$



Procedure:

1. Draw two semicircles of radii a and b (from the previous slide).
2. Draw radial lines along the corresponding Butterworth angles (π/n) and locate the n^{th} -order Butterworth poles (shown by crosses) on the two circles.
3. The location of the k^{th} Chebyshev pole is the intersection of the horizontal projection and the vertical projection from the corresponding k^{th} Butterworth poles on the outer and the inner circle, respectively.



Chebyshev Values / Table

$$\mathcal{H}(s) = \frac{K_n}{C'_n(s)} = \frac{K_n}{s^n + a_{n-1}s^{n-1} + \dots + a_1s + a_0}$$

$$K_n = \begin{cases} a_0 & n \text{ odd} \\ \frac{a_0}{\sqrt{1+\epsilon^2}} = \frac{a_0}{10^{\hat{r}/20}} & n \text{ even} \end{cases}$$

n	a_0	a_1	a_2	a_3
1	1.9652267			
2	1.1025103	1.0977343		
3	0.4913067	1.2384092	0.9883412	
4	0.2756276	0.7426194	1.4539248	0.9528114

1 db ripple
($\hat{r} = 1$)



Other Filter Types:

Chebyshev Type II = Inverse Chebyshev Filters

- Chebyshev filters passband has ripples and the stopband is smooth.
- **Instead:** this has **passband** have **smooth** response and **ripples** in the stopband.
- Exhibits maximally flat passband response and equi-ripple stopband
- **Cheby2** in MATLAB

$$|\mathcal{H}(\omega)|^2 = 1 - |\mathcal{H}_C(1/\omega)|^2 = \frac{\epsilon^2 C_n^2(1/\omega)}{1 + \epsilon^2 C_n^2(1/\omega)}$$

Where: \mathcal{H}_c is the Chebyshev filter system from before

- Passband behavior, especially for small ω , is **better** than Chebyshev
- **Smallest transition band** of the 3 filters (Butter, Cheby, Cheby2)
- Less time-delay (or phase loss) than that of the **Chebyshev**
- Both needs the **same order n** to meet a set of specifications.
- \$\$\$ (or number of elements):
Cheby < Inverse Chebyshev < Butterworth (of the same **performance** [not order])



Other Filter Types:

Elliptic Filters (or Cauer) Filters

- Allow **ripple** in **both** the passband and the stopband,
→ we can achieve **tighter** transition band

$$|\mathcal{H}(j\omega)| = \frac{1}{\sqrt{1 + \epsilon^2 R_n^2(\omega)}}$$

Where: R_n is the n^{th} -order Chebyshev rational function determined from a given ripple spec.
 ϵ controls the ripple

$$G_p = \frac{1}{\sqrt{1 + \epsilon^2}}$$

- Most efficient (η)
 - the **largest ratio** of the passband gain to stopband gain
 - **or** for a given ratio of passband to stopband gain, it requires the **smallest transition band**

→ in MATLAB: **ellipord** followed by **ellip**



In Summary

Filter Type	Passband Ripple	Stopband Ripple	Transition Band	MATLAB Design Command
Butterworth	No	No	Loose	<code>butter</code>
Chebyshev	Yes	No	Tight	<code>cheby</code>
Chebyshev Type II (Inverse Chebyshev)	No	Yes	Tight	<code>cheby2</code>
Elliptic	Yes	Yes	Tightest	<code>ellip</code>



Announcements:

- Assignment 1 Solutions:
 - Extended to Today!
 - Solution for Problem 7 Posted
 - “Best of” Submissions
 - Did you see / have a “best of” submission – let us know about it
 - We’ll post these to the class webpage (with permission of the student of course)
- Lab 3 (Experiment 4)
 - **Will run on Week 9!**
 - ∴ Week 8 has the ANZAC holiday



Next Time in Linear Systems

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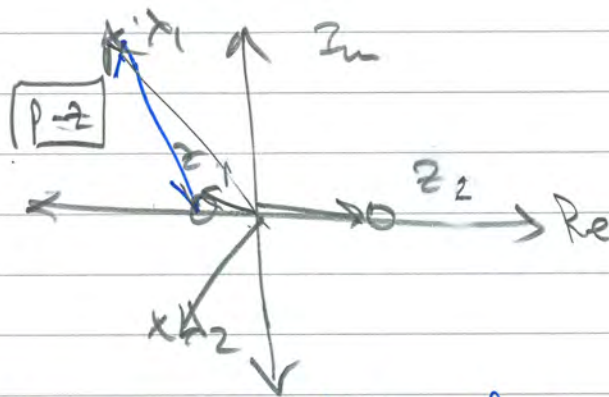


→ FILTER DESIGN BY POLE/ZERO PLACEMENT

$$H(s) = \frac{P(s)}{Q(s)} = b_n \frac{(s-z_1)(s-z_2)\dots(s-z_n)}{(s-\lambda_1)(s-\lambda_2)\dots(s-\lambda_m)}$$

z: ZEROS

λ: POLES



→ BUTTERWORTH FILTERS IN POLE/ZERO NOTATION

$$H(j\omega) = \frac{1}{\sqrt{1 + \omega^{2n}}}$$

Normalized form: $\omega_c = 1$

$s = j\omega$

$$H(s) = \frac{1}{\sqrt{1 + \left(\frac{s}{j}\right)^{2n}}}$$

Why: $\omega = \frac{s}{j}$

$$H(s) = \frac{1}{1 + \left(\frac{s}{j}\right)^{2n}}$$

$$H(s)^2 = \frac{1}{1 + (s/j)^{2n}} = \frac{1}{1 + \frac{s^{2n}}{j^{2n}}}$$

POLES ARE GIVEN BY:

poles at: $s^{2n} = \Rightarrow \left(\begin{matrix} 0 \\ j \end{matrix} \right)^{2n}$] ^{why?} $\therefore (1 + \frac{s^{2n}}{j^{2n}}) = 0 \Rightarrow \frac{s^{2n}}{j^{2n}} = -1$

Recall that:

$$\therefore \underline{s^{2n} = -j^{2n}}$$

$$-1 = e^{j\pi(2k-1)}$$

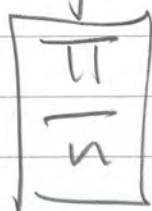
$$e^{j\pi/2} = j$$

$$\Rightarrow \underline{s^{2n} = e^{j\pi(2k-1 + \frac{n}{2})}}$$

$k = \text{integer}$

→ The poles can be visualized on a pole-zero diagram: (ex. 7.22)

→ OBSERVE that all poles have a unit magnitude and are located on a unit circle in the s-plane separated by an angle



→ Butterworth Transfer function

$$H(s) = \frac{1}{B(s)} = \frac{1}{s^n + a_{n-1}s^{n-1} + \dots + a_1s + 1}$$

where: $a_{n-1}, \dots, a_1 = \text{from Butterworth tables}$